120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to1.5Vdc output; 120A Output Current

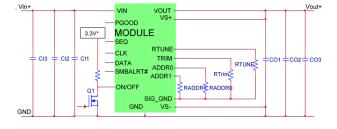




RoHS Compliant

Applications

- Networking equipment
- Telecommunications equipment
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



Features

- Compliant to RoHS EU Directive 2002/95/EC (Z versions)
- Compliant to IPC-9592 (September 2008), Category 2
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- Wide Input voltage range (7Vdc-14 Vdc)
- Output voltage programmable from 0.6Vdc to 1.5Vdc via external resistor or PMBus™# commands
- Digital interface through the PMBus protocol
- Ability to parallel multiple modules (optional)
- Digital sequencing
- Fast digital loop control
- Power Good signal
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Output overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Cost efficient open frame design
- Small size: 53.8 x 31.7 x 13.3 mm [2.118" x 1.248" x 0.524"]
- Wide operating temperature range [-40°C to 85°C]
- UL* 60950-1 2nd Ed.+A1+A2 Recognized, CSA† C22.2 No. 60950-1-07+A1+A2 Certified, and VDE[‡] (EN60950-1 2nd Ed.+A11+A1+A12+A2) Licensed
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

The 120A Digital TeraDLyn x^{TM} power modules are non-isolated dc-dc converters that can deliver up to 120A of output current. These modules operate over a 7 to 14Vdc input range and provide a precisely regulated output voltage from 0.6 to 1.5Vdc. The output voltage is programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, Power Good signal and overcurrent, overvoltage and overtemperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes a real time compensation loop that allows optimizing the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- † CSA is a registered trademark of Canadian Standards Association.
- † VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
 ** ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are only absolute stress ratings, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage - Continuous	All	V_{IN}	-0.3	15	V
SEQ, ADDRO, ADDR1, RTUNE, RTRIM, SYNC, VS+, ON/OFF	All		-0.3	3.6	V
CLK, DATA, SMBALERT#	All		-0.3	3.6	V
Operating Ambient Temperature	All	T _A	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T _{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V _{IN}	7	_	14	Vdc
Maximum Input Current	All	I _{IN,max}			29	Adc
($V_{IN}=7V$ to 14V, $I_{O}=I_{O,max}$)						
Input No Load Current	V _{O,set} = 0.6 Vdc	I _{IN,No load}		160		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	$V_{O,set} = 1.5Vdc$	I _{IN1No load}		200		mA
Input Stand-by Current ($V_{IN} = 12Vdc$, module disabled)	All	I _{IN,stand-by}		62		mA
Inrush Transient	All	I²t		1		A ² s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1 μ H source impedance; V_{IN} =0 to 14 V_{IO} = I_{Omax} ; See Test Configurations)	All			5		mAp-p
Input Ripple Rejection (120Hz)	All			-54		dB
Output Voltage Set-point Tolerance over output voltage range from 0.5 to 1.5V						
0 to 85°C	All	V _{O, set}	-0.7		+0.7	% V _{O, set}
-40 to 85°C	All	V _{O, set}	-1.0		+1.0	% V _{O, set}
Voltage Regulation ¹						
Line Regulation	(V _{IN} =V _{IN, min} to V _{IN, max})			2		mV
	(12V _{IN} ±20%)			1		mV
Load (I ₀ =I _{0, min} to I _{0, max}) Regulation	All			4		mV

 $^{^1 \}text{Worst case Line and load regulation data, all temperatures, from design verification testing as per IPC9592}.$

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Adjustment Range (selected by an external resistor)	All	V _{OUT}	0.6		1.5	Vdc
PMBus Adjustable Output Voltage Range	All	V _{OUT}	0.6		1.5	Vdc
PMBus Output Voltage Adjustment Step Size	All			98		μV
Remote Sense Range	All				0.3	Vdc
Output Ripple and Noise on nominal output ($V_{IN}=V_{IN,nom}$ and $I_{O}=I_{O,min}$ to $I_{O,max}$ Co = 1500 μF						
Peak-to-Peak (Full bandwidth)					30	$mV_{\text{pk-pk}}$
RMS (Full bandwidth)	All				12	$mV_{rms} \\$
External Capacitance ²						
Minimum output capacitance	All	$C_{O,min}$	1500	_	_	μF
Maximum output capacitance	All	Co, max		_	40000	μF
Output Current (in either sink or source mode)	All	lo	0.005*		120	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		110		% I _{o,max}
Output Short-Circuit Current	All	l _{O1, s/c} , l _{O1, s/c}		40		Arms
(Vo≤250mV) (Hiccup Mode)						
Efficiency	$V_{O,set} = 0.6Vdc$	η		88.2		%
	$V_{O, set} = 0.8Vdc$	η		90.9		%
V _{IN} = 12Vdc, T _A =25°C	V _{O,set} = 1.0Vdc	η		92.1		%
$I_0=I_{0, mox}$, $V_0=V_{0, set}$	V _{O,set} = 1.2Vdc	η		93.0		%
	$V_{O, set} = 1.5 Vdc$	η		94.0		%
Switching Frequency	All	f _{sw}	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-15		+15	%
High-Level Input Voltage	All	V _{IH,SYNC}	2.5			V
Low-Level Input Voltage	All	V _{IL,SYNC}			1.1	V
Minimum Pulse Width, SYNC	All	tsync	256			ns

^{*} Minimum load on module should be 5mA

² External capacitors may require using the new Tunable Loop[™] feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop[™] section for details.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I ₀ =0.8I _{0, max} , T _A =40°C) Telecordia Issue 2 Method 1 Case 3	All		11,556,226		Hours
Weight - Module with SMT Pins			57 (2.01)		g (oz.)
Module with Through Hole Pins			59 (2.08)		g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
($V_{IN} = V_{IN,min}$ to $V_{IN,max}$; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	lін	_	_	1	mA
Input High Voltage	All	VIH	2	_	3.6*	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
Input High Current	All	Іін	_	_	10	μΑ
Input High Voltage	All	VIH	2	_	3.6*	Vdc
Logic Low (Module OFF)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN,nom}, I_0=I_{0,max}, V_0)$ to within ±1% of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until $V_0 = 10\%$ of V_0, set)	All	Tdelay	_	10	_	ms
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo, set)	All	Tdelay	ı	2	_	ms
Output voltage Rise time (time for V_0 to rise from 10% of V_0 , set to 90% of V_0 , set)	All	Trise	-	5	_	msec
Output voltage overshoot ($T_A = 25^{\circ}C$) $V_{IN} = V_{IN, min}$ to $V_{IN, mox, I_O} = I_{O, min}$ to $I_{O, max}$) With or without maximum external capacitance		Output			3.0	% V _{O, set}
Over Temperature Protection (See Thermal Considerations section)	All	T _{ref}		135		°C
PMBus Over Temperature Warning Threshold	All	Twarn		125		°C
	-			-		

^{*}Use external resistive voltage divider to step down higher logic voltages

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Feature Specifications (cont.)

Parameter		Device	Symbol	Min	Тур	Max	Units
Tracking Accuracy	(Power-Up: 0.5V/ms)	All	VSEQ -Vo			100	mV
	(Power-Down: 0.5V/ms)	All	VSEQ -Vo			100	mV
($V_{IN,min}$ to $V_{IN,max}$; $I_{O,min}$ to	I _{O, max} VSEQ < Vo)						
Input Undervoltage Loc	kout						
Turn-on Threshold		All				7	Vdc
Turn-off Threshold		All		6.75			Vdc
Hysteresis	Hysteresis				0.25		Vdc
PMBus Adjustable Input	PMBus Adjustable Input Under Voltage Lockout Thresholds			7		14	Vdc
Resolution of Adjusta	ble Input Under Voltage Threshold	All				5.8	mV
PGOOD (Power Good)							
Signal Interface Oper	n Drain, $V_{\text{supply}} \leq 5VDC$						
Overvoltage threshol	d for PGOOD ON	All			110		$%V_{O, set}$
Overvoltage threshol	d for PGOOD OFF	All			110		%V _{O, set}
Undervoltage threshold for PGOOD ON		All			90		$%V_{O,set}$
Undervoltage threshold for PGOOD OFF		All			90		%V _{O, set}
Pulldown resistance of PGOOD pin		All				2	Ω
Sink current capabilit	ty into PGOOD pin	All				50	mA

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

8Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics				•		
Input High Voltage (CLK, DATA)		VIH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			1.1	V
Input high level current (CLK, DATA)		Iн			0.5	μΑ
Input low level current (CLK, DATA)		l _{IL}			4	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{OUT} =4mA	Vol			0.25	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	5		55	nA
Pin capacitance		Co			10	pF
PMBus Operating frequency range	Slave Mode	Fрмв	10		1000	kHz
Data hold time		thd:dat		0		ns
Data setup time		tsu:dat		100		ns
Measurement System Characteristics						
Read delay time		toly		110		μs
Output current measurement range		I _{RNG}	0		135	А
Output current measurement resolution		IRES		250		mA
Output current measurement accuracy	-40°C to +85°C	lacc			±5	% of Io,max
V _{OUT} measurement range		Vout	0		2.0	V
V _{OUT} measurement accuracy		V _{OUT(gain)}		±1		% of Vo,max
V _{OUT} measurement resolution		V _{OUT(res)}		0.61		mV
V_{IN} measurement range		V _{IN}	0		16	V
V _{IN} measurement accuracy		V _{IN(gain)}		±2		%
V _{IN} measurement resolution		V _{IN(res)}		5.8		mV
Temperature measurement range		TMEAS	-25		150	°C
Temperature measurement accuracy		T _{MEAS(gain)}	-8		8	°C
Temperature measurement resolution		T _{MEAS(res)}		0.08		°C

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 0.6Vo and 25°C.

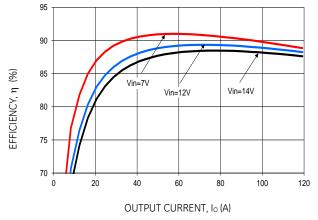


Figure 1. Converter Efficiency versus Output Current.

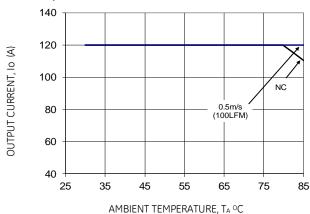
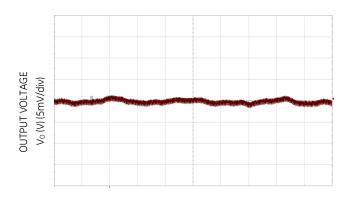
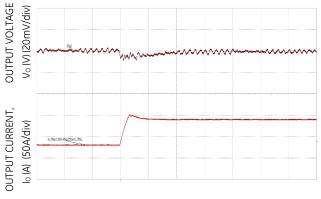


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs/div)

Figure 3. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{0,max}$).



TIME, t (200µs /div)

Figure 4. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= $12 \times 47 \mu F + 10 \times 1000 \mu F$, $R_{TUNE} = 3.01 k\Omega$.

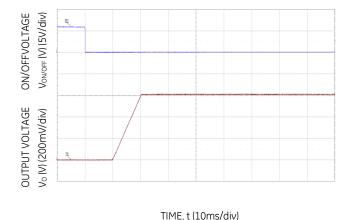


Figure 5. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).



TIME, t (10ms/div)

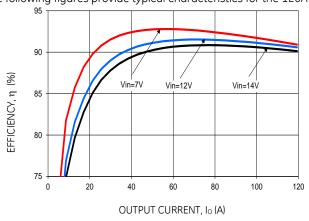
Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

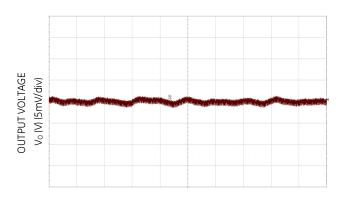
The following figures provide typical characteristics for the 120A TeraDLynx™ at 0.8Vo and 25°C

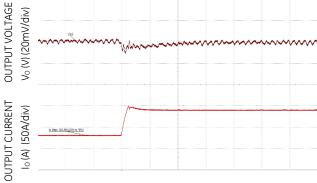


1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 80 0.5m/s (100LFM) 60 40 25 35 45 55 65 75 85 AMBIENT TEMPERATURE, TA °C

Figure 7. Converter Efficiency versus Output Current.

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.





TIME, t (50 μ s/div) Figure 9. Typical output ripple and noise (C_O=12x47 μ F ceramic + 10x470 μ F polymer, VIN = 12V, Io = Io,max,)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .

TIME, t (200 µs /div)

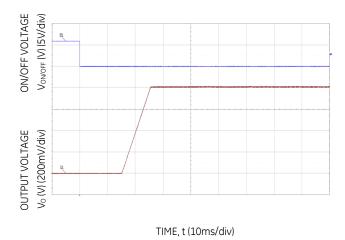




Figure 11. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 12. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{O,max}$).

TIME, t (10ms/div)

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 1.0Vo and 25°C.

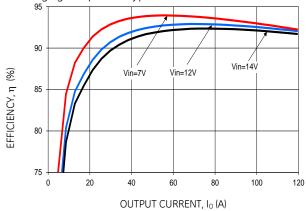


Figure 13. Converter Efficiency versus Output Current.

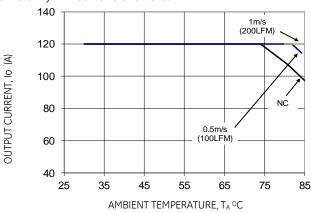


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

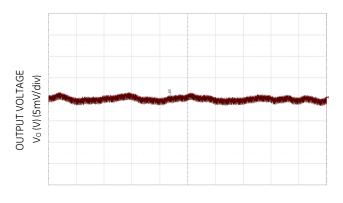


Figure 15. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{0,max,}$)

TIME, t (50µs/div)

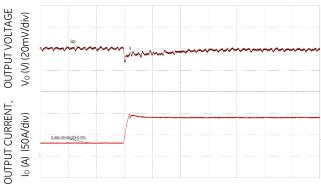


Figure 16. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .

TIME, t (200 µs /div)

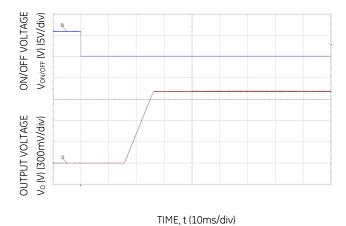


Figure 17. Typical Start-up Using On/Off Voltage (Io = Io,max).



Figure 18. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{O,max}$).

TIME, t (10ms/div)

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 1.2Vo and 25°C.

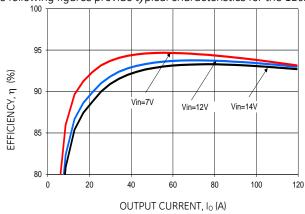


Figure 19. Converter Efficiency versus Output Current.

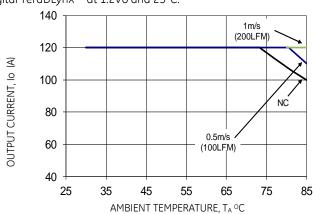
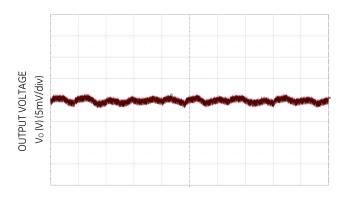
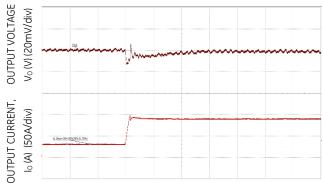


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

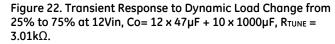


TIME, t (50µs/div)



TIME, t (200µs /div)

Figure 21. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{0,max}$)



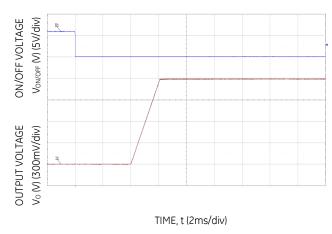


Figure 23. Typical Start-up Using On/Off Voltage (Io = Io,max).



TIME, t (10ms/div)

Figure 24. Typical Start-up Using Input Voltage ($V_{IN}=12V$, $I_0=I_{0,max}$).

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 1.5Vo and 25°C.

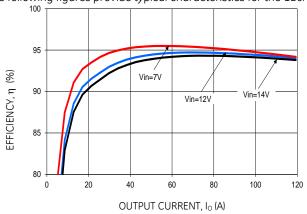


Figure 25. Converter Efficiency versus Output Current.

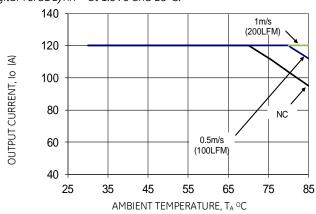
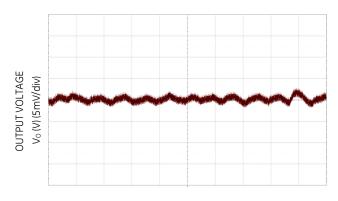
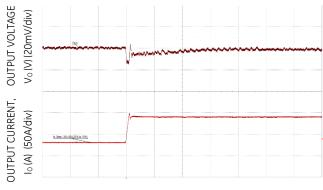


Figure 26. Derating Output Current versus Ambient Temperature and Airflow.



 $\label{eq:TIME} \text{TIME, t (50}\mu\text{s/div)}$ Figure 27. Typical output ripple and noise (Co=12x47 μF

ceramic + 10x470µF polymer, VIN = 12V, Io = Io,max,)



TIME, t (200µs /div)

Figure 28. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= $12 \times 47 \mu F + 10 \times 1000 \mu F$, $R_{TUNE} = 3.01 k \Omega$.

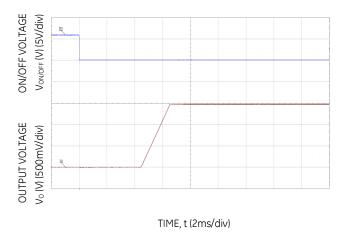
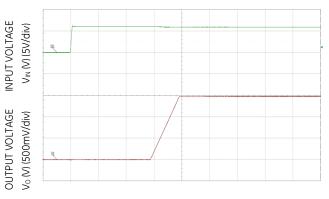


Figure 29. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).



TIME, t (2ms/div)

Figure 30. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Design Considerations

Input Filtering

The 120A TeraDLynx[™] module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 120A of load current with 4x470 + 12x22 + 12x4.7 μF and 2x470 + 6x22 + 12x4.7 μF input capacitor combinations.

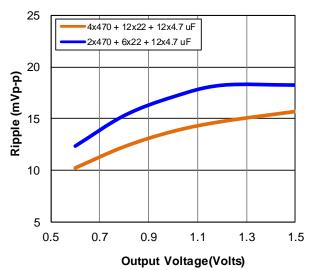


Figure 31. Input ripple voltage for various output voltages with two input capacitor combinations at 120A load. Input voltage is 12V.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of $12\times22~\mu\text{F}$ ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 32 provides output ripple information for capacitance of ~3574uF (47µF (1210 ceramic) x 12 + 10µF (0805 ceramic) + 0.1µF (0402) x4 + 1000µF (polymer) x 3) at various Vo and a full load current of 120A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal

performance of the module can be achieved by using the Tunable Loop™ feature described later in this data sheet.

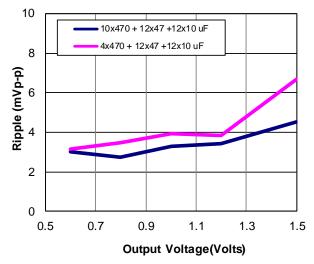


Figure 32. Peak to peak output ripple voltage for various output voltages with external capacitors at the output (120A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., ANSI/UL 60950-1 2nd Revised October 14, 2014, CSA C22.2 No. 60950-1-07, Second Ed. + A2:2014 (MOD), DIN EN 60950-1:2006 + A11:2009 + A1:2010 +A12:2011, + A2:2013 (VDE0805 Teil 1: 2014-08)(pending).

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a slow-blow fuse. When the input voltage is \leq 8V, the recommendation is to use two 25A Littelfuse 456 series or equivalent fuses in parallel. For input voltages > 8V, a single 40A Littelfuse series 456 or equivalent fuse is recommended.

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7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Analog Feature Descriptions

Remote On/Off

The TeraDLynx 120A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF can controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 120A Digital TeraDLynx[™] power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

Digital On/Off

Please see the Digital Feature Descriptions section.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior on the output for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module will start into a pre biased output on output as long as the pre bias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.6 to 1.5Vdc, as shown in Table 1, by connecting a resistor between the Trim and SIG_GND pins of the module as shown in Fig 33.

Without an external resistor between the Trim pin and SIG_GND pins, the output of the module will be 0.1 Vdc. The value of the trim resistor, R_{Trim} for a desired output voltage, should be selected as shown in Table 1.

The trim resistor is only determined during module initialization and hence cannot be used for dynamic output voltage adjustment

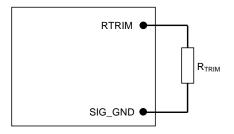


Figure 33. Circuit configuration for programming output voltage using an external resistor.

Table 1

V _O , set	Rtrim	V _{O, set}	Rtrim	V _{O, set}	Rtrim
(V)	(Ω)	(V)	(Ω)	(V)	(Ω)
0.600	1090	1.000	2870	1.400	18900
0.620	1140	1.020	3050	1.420	23200
0.640	1180	1.040	3240	1.440	29800
0.660	1230	1.060	3480	1.460	40200
0.680	1290	1.080	3700	1.480	60400
0.700	1330	1.100	3920	1.500	115000
0.720	1380	1.120	4220		
0.740	1470	1.140	4530		
0.760	1560	1.160	4990		
0.780	1640	1.180	5360		
0.800	1740	1.200	5900		
0.820	1820	1.220	6420		
0.840	1930	1.240	6980		
0.860	2030	1.260	7680		
0.880	2130	1.280	8450		
0.900	2230	1.300	9420		
0.920	2340	1.320	10400		
0.940	2460	1.340	11700		
0.960	2610	1.360	13500		
0.980	2710	1.380	15800		

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for the output. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.3V.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

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Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

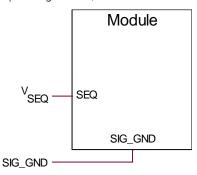


Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Digital Sequencing

The module can support digital sequencing by allowing control of the turn-on delay and rise times as well as turn-off and fall times.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Overcurrent Protection (OCP)

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. OCP response time is programmable through manufacturer specific commands. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable Overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 135 °C (typ) is exceeded at the thermal reference point $T_{\text{ref.}}$ Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Adjustable Overcurrent Warning/Shutdown

Please see the Digital Feature Descriptions section.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation for the associated output is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Synchronization

The module switching frequency is capable of being synchronized to an external signal frequency within a specified range. Synchronization is done by using the external signal applied to the SYNC pin of the module as shown in Fig. 35, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

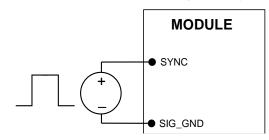


Figure 35. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

Digital Compensator

The TJT120 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors

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are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The TJT120 comes with default compensation values programmed into the non-volatile memory of the module. These digital compensation values can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This can be done by two different methods.

- By allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. This selection is made via a resistor RTune connected between the RTUNE and SIG_GND pins as shown in Fig. 35. Table 2 shows various pre-tuned compensation combinations recommended for various external capacitor combinations.
- Using PMBus to change compensation parameters in the module.

Note that during initial startup of the module, compensation values that are stored in non-volatile memory are used. If a resistor RTune is connected to the module, then the compensation values are changed to ones that correspond to the value of RTUNE. If RTUNE is open however, no change in compensation values is made. Finally, if the user chooses to do so, they can overwrite the compensation values via PMBus commands.

Recommended values of R_{TUNE} for different output capacitor combinations are given in Table 2. If no RTUNE is used, the default compensation values are used.

The TJT120 pre-tuned compensation can be divided into three different banks (COMP1, COMP2, COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of 20 different sets of compensation coefficients pre-calculated for different values of output capacitance. The three banks are set up as follows:

 COMP1: Recommended for the case where all of the output capacitance is composed of only ceramic

- capacitors. The range of external output capacitance is from 1470 μF to a maximum value of 17640 $\mu F)$
- COMP2: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size. The range of output capacitance is from 2564 µF to a maximum of 30564 uF. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of $12 \times 47 \mu F$ ceramics $+ 25 \times 1000 \mu F$ polymer capacitors, and selecting RTUNE = $5.36k\Omega$, transient deviation can be as low as 25 mV, for a 50% load step (0 to 85A).
- COMP3: Suitable for a mix of ceramic and higher ESR polymers or electrolytic capacitors, with output capacitance ranging from a minimum of 2204 µF to a maximum of 30084 µF.

Selecting R_{TUNE} according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of an 60A to 120A step change (50% of full load), with an input voltage of 12V. Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.

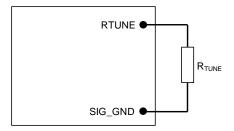


Figure 36. Circuit diagram showing connection of R_{TUNE} to tune the control loop of the module.

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Table 2. Recommended RTUNE Compensation.

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (µF)**	R _{TUNE} resistor (Ω)	R _{TUNE} Index	KD	KI	КР	AP
D	efault Compensation Value	es	OPEN		375	2	37	150
Ceramic	10 x 47μF + 10 x 100μF	1398	29.1	0	375	2	37	150
Ceramic	12 x 47μF + 12 x 100μF	1644	88.7	1	441	3	44	150
Ceramic	14 x 47μF + 14 x 100μF	1890	150	2	506	3	51	150
Ceramic	16 x 47μF + 16 x 100μF	2136	213	3	572	3	57	150
Ceramic	19 x 47μF + 19 x 100μF	2505	280	4	671	3	67	150
Ceramic	22 x 47μF + 22 x 100μF	2874	348	5	770	4	77	150
Ceramic	25 x 47μF + 25 x 100μF	3243	417	6	869	4	87	150
Ceramic	28 x 47μF + 28 x 100μF	3612	493	7	968	4	97	150
Ceramic	31 x 47μF + 31 x 100μF	3981	569	8	1067	4	107	150
Ceramic	34 x 47μF + 34 x 100μF	4350	642	9	1166	4	117	150
Ceramic	38 x 47μF + 38 x 100μF	4842	723	10	1297	5	130	150
Ceramic	42 x 47μF + 42 x 100μF	5334	806	11	1429	5	143	150
Ceramic	48 x 47μF + 48 x 100μF	6072	898	12	1627	5	163	150
Ceramic	55 x 47μF + 55 x 100μF	6933	938	13	1858	5	186	150
Ceramic	63 x 47μF + 63 x 100μF	7917	1090	14	2121	6	212	150
Ceramic	72 x 47μF + 72 x 100μF	9024	1180	15	2418	6	242	150
Ceramic	82 x 47μF + 82 x 100μF	10254	1290	16	2748	7	275	150
Ceramic	93 x 47μF + 93 x 100μF	11607	1400	17	3110	7	311	150
Ceramic	105 x 47μF + 105 x 100μF	13083	1520	18	3506	7	351	150
Ceramic	120 x 47μF + 120 x 100μF	14928	1640	19	4000	8	400	150
Ceramic + Polymer	12 x 47μF + 2 x 1000μF	2672	1760	20	501	3	300	220
Ceramic + Polymer	12 x 47μF + 3 x 1000μF	3672	1890	21	688	3	413	220
Ceramic + Polymer	12 x 47μF + 4 x 1000μF	4672	2030	22	876	3	525	220
Ceramic + Polymer	12 x 47μF + 5 x 1000μF	5672	2150	23	1063	4	638	220
Ceramic + Polymer	12 x 47μF + 6 x 1000μF	6672	2320	24	1250	4	750	220
Ceramic + Polymer	12 x 47μF + 7 x 1000μF	7672	2460	25	1438	4	860	220
Ceramic + Polymer	12 x 47μF + 8 x 1000μF	8672	2640	26	1625	5	975	220
Ceramic + Polymer	12 x 47μF + 9 x 1000μF	9672	2840	27	1813	5	1088	220
Ceramic + Polymer	12 x 47μF + 10 x 1000μF	10672	3010	28	2000	5	1200	220
Ceramic + Polymer	12 x 47μF + 11 x 1000μF	11672	3200	29	2187	5	1312	220
Ceramic + Polymer	12 x 47μF + 12 x 1000μF	12672	3400	30	2375	5	1425	220
Ceramic + Polymer	12 x 47μF + 13 x 1000μF	13672	3650	31	2562	6	1537	220
Ceramic + Polymer	12 x 47μF + 15 x 1000μF	15672	3880	32	2937	6	1762	220
Ceramic + Polymer	12 x 47μF + 17 x 1000μF	17672	4120	33	3312	6	1987	220
Ceramic + Polymer	12 x 47μF + 19 x 1000μF	19672	4420	34	3687	7	2212	220
Ceramic + Polymer	12 x 47μF + 21 x 1000μF	21672	4700	35	4061	7	2437	220
Ceramic + Polymer	12 x 47μF + 23 x 1000μF	23672	5050	36	4436	7	2662	220
Ceramic + Polymer	12 x 47μF + 25 x 1000μF	25672	5360	37	4811	8	2887	220
Ceramic + Polymer	12 x 47μF + 27 x 1000μF	27672	5760	38	5186	8	3112	220
Ceramic + Polymer	12 x 47μF + 30 x 1000μF	30672	6120	39	5748	8	3449	220

^{**} Total output capacitance includes the capacitance inside the module is 4 x 47 μ F (3m Ω ESR).

Note: The capacitors used in the digital compensation Loop tables are $47\mu\text{F}/3~\text{m}\Omega$ ESR ceramic, $100u\text{F}/3.2m\Omega$ ceramic, $1000~\mu\text{F}/6m\Omega$ ESR polymer capacitor and $820u\text{F}/19m\Omega$ ESR Polymer capacitor.

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Table 2 (continued). RTUNE compensation table

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (µF)**	R _{TUNE} resistor (Ω)	R _{TUNE} Index	KD	KI	КР	AP
Ceramic + Electrolytic	12 x 47μF + 2 x 820μF	2312	6570	40	176	2	176	220
Ceramic + Electrolytic	12 x 47μF + 3 x 820μF	3312	7060	41	238	3	238	220
Ceramic + Electrolytic	12 x 47μF + 4 x 820μF	3952	7590	42	301	3	301	220
Ceramic + Electrolytic	12 x 47μF + 5 x 820μF	4772	8160	43	363	3	363	220
Ceramic + Electrolytic	12 x 47μF + 6 x 820μF	5592	8870	44	426	4	426	220
Ceramic + Electrolytic	12 x 47μF + 7 x 820μF	6412	9530	45	488	4	488	220
Ceramic + Electrolytic	12 x 47μF + 8 x 820μF	7312	10400	46	550	4	550	220
Ceramic + Electrolytic	12 x 47μF + 9 x 820μF	8052	11300	47	613	4	613	220
Ceramic + Electrolytic	12 × 47μF + 10 × 820μF	8872	12400	48	675	5	675	220
Ceramic + Electrolytic	12 x 47μF + 11 x 820μF	9692	13700	49	738	5	738	220
Ceramic + Electrolytic	12 x 47μF + 12 x 820μF	10512	15000	50	800	5	800	220
Ceramic + Electrolytic	12 x 47μF + 14 x 820μF	12152	16700	51	925	5	925	220
Ceramic + Electrolytic	12 x 47μF + 16 x 820μF	13792	18700	52	1050	6	1050	220
Ceramic + Electrolytic	12 x 47μF + 18 x 820μF	15432	21000	53	1174	6	1174	220
Ceramic + Electrolytic	12 × 47μF + 20 × 820μF	17072	24000	54	1299	6	1299	220
Ceramic + Electrolytic	12 × 47μF + 23 × 820μF	19532	28000	55	1486	7	1486	220
Ceramic + Electrolytic	12 x 47μF + 26 x 820μF	21992	33000	56	1674	7	1674	220
Ceramic + Electrolytic	12 × 47μF + 29 × 820μF	24452	40200	57	1861	8	1861	220
Ceramic + Electrolytic	12 × 47μF + 32 × 820μF	26912	50500	58	2048	8	2048	220
Ceramic + Electrolytic	12 × 47μF + 36 × 820μF	30192	68000	59	2298	8	2298	220

^{**} Total output capacitance includes the capacitance inside the module is $4 \times 47 \mu F$ (3m Ω ESR).

Note: The capacitors used in the digital compensation Loop tables are $47\mu\text{F}/3~\text{m}\Omega$ ESR ceramic, $100u\text{F}/3.2m\Omega$ ceramic, $1000~\mu\text{F}/6m\Omega$ ESR polymer capacitor and $820u\text{F}/19m\Omega$ ESR Electrolytic capacitor.

Power Module Wizard

GE offers a free web based easy to use tool that helps users simulate the Tunable Loop performance of the TJT170. Go to http://ge.transim.com/pmd/Home and sign up for a free account and use the module selector tool. The tool also offers downloadable Simplis/Simetrix models that can be used to assess transient performance, module stability, etc.

Bin 'a' and Bin 'b' settings using the models available through Power Module Wizard

The TJT170 module has a built-in non-linear compensation adjustment to speed up its transient response to dynamic loading conditions. When the module senses a load transition in progress, it automatically adjusts the KD, KI, KP settings to higher values and then reverts to the values set before the transient conditions. The adjustment of the PID coefficients is as follows:

Steady State			Transient Condition				
Bin 'a' – User set valu	ues based on RTUNE o	or programmed	Bin 'b' - Controller adjusted values for duration of transient				
KD	KI	KP	KD KI KP				
Α	В	X	2 x A	2 x B	2 x C		

For determining the voltage response to a current load transient, it is more accurate to use the Bin 'b' settings corresponding to the selected KD, KI, KP values. For Loop Stability Simulations, the selected PID values corresponding to Bin 'a' should be used.

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Digital Feature Descriptions

PMBus Interface Capability

The 120A TeraDLynx power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from www.pmbus.org. The modules support a subset of version 1.1 of the specification (see Table 4 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

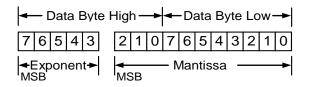
Communication over the module PMBus interface supports the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 4 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two-byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa \times 2 Exponent

PMBus Addressing

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 3 (E96 series resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

The user must know which I^2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the

Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

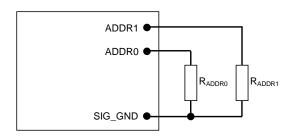


Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

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	PMBus Address Table										
		ADDR1 Resistor Values									
ADDRO Resistor Values	4.99K	15.4k	27.4K	41.2K	54.9K	71.5K	90.9K	110K	137K	162K	191K
4.99K	1	13	25	37	49	61	73	85	97	109	121
15.4K	2	14	26	38	50	62	74	86	98	110	122
27.4K	3	15	27	39	51	63	75	87	99	111	123
41.2K	4	16	28	40	52	64	76	88	100	112	124
54.9K	5	17	29	41	53	65	77	89	101	113	125
71.5K	6	18	30	42	54	66	78	90	102	114	126
90.9K	7	19	31	43	55	67	79	91	103	115	127
110K	8	20	32	44	56	68	80	92	104	116	64
137K	9	21	33	45	57	69	81	93	105	117	64
162K	10	22	34	46	58	70	82	94	106	118	64
191K	11	23	35	47	59	71	83	95	107	119	64
232K	12	24	36	48	60	72	84	96	108	120	64

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7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Operation (01h)

This is a paged register. The OPERATION command can be used to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled 1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	Χ	CPA
Default Value	1	0	1	X	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

PMBus Adjustable Soft Start Rise Time

The soft start rise time of module output is adjustable in the module via PMBus. The TON_RISE command can set the rise time in ms, and allows choosing soft start times between 1 and 1000ms.

Output Voltage Adjustment Using the PMBus

Two PMBus commands are available to change the output voltage setting. The first, VOUT_COMMAND can set the output voltage directly. The second, VOUT_TRIM is used to apply an offset to the commanded output voltage.

Since the output voltage can be set using an external RTrim resistor as well, an additional PMBus command MFR_VOUT_SET_MODE is used to tell the module whether the VOUT_COMMAND is used to directly set output voltage or whether RTrim is to be used. If MFR_VOUT_SET_MODE is set to where bit position 7 is set at 1, then VOUT_COMMAND is ignored and output voltage is set solely by RTrim. If bit 7 of MFR_VOUT_SET_MODE is set to 0, then output voltage is set using VOUT_COMMAND, and the value of RTrim is only used at startup to set the output voltage.

The second output voltage adjustment command VOUT_TRIM works in either case to provide a fixed offset to the output voltage. This allows PMBus adjustment of the output voltage irrespective of how MFR_VOUT_SET_MODE is set and allows digital adjustment of the output voltage setting even when RTrim is used.

For all digital commands used to set or adjust the output voltage via PMBus, the resolution is $98\mu V$.

Output Voltage Margining Using the PMBus

The output voltage of the module can be margined via PMBus between 0.6 and 1.5V. The margining voltage can be adjusted in 98µV steps.

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ_TEMPERATURE1, READ_TEMPERATURE_2 are mapped to module temperature and internal temperature of the PWM controller, respectively. The temperature readings are returned in °C and in two bytes.

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PMBus Adjustable Output Over, Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold. The default value is configured to be 112.5% of the commanded output. The command VOUT_UV_FAULT_LIMIT sets the threshold that detects an output under voltage fault. The default values are 87.5% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command possible values are 7 to 14V and for the VIN_OFF command, possible values are 6.75V to 14V. Both VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes.

Measurement of Output Current, Output Voltage and Input Voltage

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

Measuring Output Current Using the PMBus

The module measures output current by using a signal derived from the switching FET currents. The current gain factor is accessed using the IOUT_CAL_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The READ_IOUT command provides module average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the Linear data format.

Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ_VOUT command. The command returns two bytes of data in Linear format.

Measuring Input Voltage Using the PMBus

The module provides input voltage information using the READ_VIN command. The command returns two bytes of data in the Linear format.

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Low	Byte
LUW	Dyte

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

High Byte

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	VOUT_OV_WARNING	0
5	VOUT_UV_WARNING	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

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Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Data	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001101 corresponds to the TJT120 series of module), while bits [7:3] in the high byte indicate the revision number of the module.

	2011 2710	
Bit Position	Flag	Default Value
7:2	Module Name	001101
1:0	Reserved	10

High Byte

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

User-Programmable Compensation Coefficients

The output voltage control compensation coefficients can be changed by the user via PMBus commands. On startup, the module uses stored values of the four compensation parameters KD, KI, KP and ALPHA. If the module detects a valid value of RTUNE connected to the module, the values of KD, KI, KP and ALPHA are then changed to the appropriate values. Beyond this, the user can use the PMBus commands listed below to overwrite the values of KD, KP, KI and ALPHA.

MFR_SPECIFIC_KP: Allows the user to program the value of the KP compensation coefficient. The allowed range is - 10922 to 10922. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 10922.

MFR_SPECIFIC_KI: Allows the user to program the value of the KI compensation coefficient. The allowed range is - 10922 to 10922. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 10922.

MFR_SPECIFIC_KD: Allows the user to program the value of the KD compensation coefficient. The allowed range is - 10922 to 10922. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 10922.

MFR_SPECIFIC_ALPHA: Allows the user to program the value of the ALPHA compensation coefficient. The allowed range is -256 to 256. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 256.

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Summary of Supported PMBus Commands
Please refer to the PMBus 1.1 specification for more details of these commands. For the registers where a range is specified, any value outside the range is ignored and the module continues to use the previous value.

Table 4

Hex	Command		Non-Volatile											
Code		Turn Module on or o	off Also	used to	Brief D	•		ltage				Memory Storage		
			711. AI30	uscu it			'	J			1			
		Format Pit Position	7	6			d Binar		1 1	0				
01	OPERATION	Bit Position	7	6	5	4 r/w	3 r/w	2	1	0		YES		
		Access	r/w	r	r/w			r/w	r	r				
		Function	On	X	_		rgin		X	X				
		Default Value	1	0	0	0	0	0	Х	Х				
		Configures the ON/ PMBus commands	OFF fun	ctionali	ty as a	combin	ation of	analog	ON/OF	F pin an	ıd			
		Format			Į	Jnsigne	d Binar	У			1			
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	1	YES		
		Access	r	r	r	r/w	r/w	r/w	r	r	1			
		Function	Χ	Х	Χ	pu	cmd	cpr	Х	сра	1			
		Default Value	0	0	0	1	0	1	Х	1	1			
											1			
03	CLEAR_FAULTS	device has been as	Clear any fault bits that may have been set, also releases the SMBALERT# signal if the device has been asserting it. Used to control writing to the module via PMBus. Copies the current register setting in											
		the module whose			e match	es the v	alue in	the dat	a byte i	nto non	-volatile			
		memory (EEPROM)	on the r	noaule		laaiaaa	al Diame				1			
		Format					d Binar		1 4	1 0				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	X	×	×	×	X				
		Function	bit7	bit6	bit5	X	X	X	X	X				
10	WRITE PROTECT	Default Value Bit5: 0 – Enables all	0	0	0	X	X	Χ	Χ	Χ]	YES		
		1 - Disables all writes except the WRITE_PROTECT, OPERATION and ON_OFF_CONFIG (bit 6 and bit7 must be 0) Bit 6: 0 - Enables all writes as permitted in bit5 or bit7 1 - Disables all writes except for the WRITE_PROTECT and OPERATION commands (bit5 and bit7 must be 0) Bit7: 0 - Enables all writes as permitted in bit5 or bit6 1 - Disables all writes except for the WRITE_PROTECT command (bit5 and bit6 must be 0)												
11	STORE_DEFAULT_ALL	Copies all current re on the module. Tak							e memo	ory (EEP	ROM)			
-		Restores all current							n the m	odule n	on-			
12	RESTORE_DEFAULT_ALL	volatile memory (EE												
		The module has MC changed	DE set	to Lined		xponen			ese valu	ies canr	not be			
20	VOUT MODE	Bit Position	7	6	5	4	3	2	1	0				
	¥301_1100E	Access	r	r	r	r	r	r	r	r				
		Function		Mode		2'	's comp		Expone					
		Default Value	0	0	0	1	0	0	1	0]			
		Set desired output of per VOUT_MODE co			range is	0.6 to	1.5V.	· ·	lied exp	onent o	of -14			
		Format	1 -	11			Mantis		1 0		Ì			
		Bit Position	15	14	13	12	11	10	9	8	Ì			
	LIGHT CC:	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	Ì	VE2		
21	VOUT_COMMAND	Function					tissa				Ì	YES		
		Default Value			-		able	1 2	1 1	1 0	-			
		Bit Position	7	6	5	4	3	2	1 1	0	ŀ			
	_	Access	r/w	r/w	r/w	r/w	r/w tissa	r/w	r/w	r/w	Ì			
		Function												
		Default Value				varı	able				j			

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command			Non-Volatile								
Code		Apply a fixed offset VOUT_COMMAND.			set outp		age fron			m resis	tor or the	Memory Storage
		Allowed range is ±3				•					_	
		Format		L	inear, tv	vo's cor	mpleme	nt binar	ˆу			
		Bit Position	15	14	13	12	11	10	9	8		
22	VOUT TRIM	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		YES
		Function Default Value	0		0	ıMan 0	tissa	Ι ο	0	0		
		Bit Position	7	0 6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	.,	., .,			tissa			.,,		
		Default Value	0	0	0	0	0	0	0	0		
		Applies an offset to	the cor	nmand	ed outn	ut volta	ne to co	alibrate	out erro	rs in se	ttina module	
		output voltage (bet										
		command VOUT_C										
		Format			inear, tv	vo's cor	mpleme	nt binar	^y			
		Bit Position	15	14	13	12	11	10	9	8		
23	VOUT CAL OFFSET	Access	r/w	r	r	r	r	r	r	r		YES
23		Function		17-	ا جامات		tissa	oal:k -	tion			
		Default Value Bit Position	7	Var 6	iable bo	sed on 4	factory 3	calibra	lion 1	0		
		Access	r	r/w	r/w	r/w	r/w	2 r/w	r/w	r/w		
		Function	'	17 VV	1700		tissa	17 00	17 VV	17 00		
		Default Value		Var	iable bo			calibra	tion			
										- (1 / -		
		Sets the target volto VOUT MODE comm										
		Format	Iuriu. Ai					nt binar	^\/			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
25	VOUT_MARGIN_HIGH	Function				Man	tissa					YES
		Default Value				Vari	able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value				Vari	able					
		Sets the target volto	age for	margini lowed r	ing the o	output I	ow. Imp	lied exp	onent c	of -14 pe	er	
		Format						nt binar	Ŷ			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
26	VOUT_MARGIN_LOW	Function					tissa					YES
		Default Value				Vari						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function Default Value					tissa able					
		Delduit value	l			vull	ubie					
		Sets the value of in range is 7 to 14V.	put volt	age at v	which th	ie modu	ule turns	on. Exp	oonent i	s fixed (at -6. Allowed	
		Format		L	inear, tv	NO'S COI	mpleme	nt bina	ry]	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
35	VIN_ON	Function			xponer				Mantiss			YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0	-	
		Access Function	r/w	r/w	r/w	r/w Man	r/w ntissa	r/w	r/w	r/w	1	
		Default Value	1	1	0	0	0	0	0	0	1	
		Dordant Value								,	J	

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief	Descrip	otion					Non-Volatile Memory Storage
		Sets the value of inp Allowed range is 6.7			vhich th	ne modu	le turns	off. Ex	oonent i	s fixed (at -6.	
		Format	13 10 14		inaar ti	vo's con	onlama	nt hina	٦,,			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
36	VIN OFF	Function	'		xponer				Mantisso			YES
30	VIIV_011	Default Value	1	1	0	1	0	0	0	1		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa	U		U		
		Default Value	1	0	1	1	0	0	0	0		
		module measureme										
		Access	r	r	r	r	r	r	r	r/w		
38	IOUT_CAL_GAIN	Function	· ·			Inte		•		.,		YES
		Default Value		Var	iable bo	ased on		calibra	tion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Inte						1
		Default Value		Var	iable bo	ased on	factory	calibra	tion			
39	IOUT_CAL_OFFSET	Returns the value of current. The exponer Format Bit Position Access Function Default Value Bit Position Access Function Default Value Bit Position Access Function Default Value	15 r 1 7 r	L 14 r E 1 1 6 r Var	2. The a inear, to 13 rexponer 1 5 r/w	llowed rowo's condition 12 rout 1 4 r/w Maniased on	ange is npleme 11 r 0 3 r/w tissa factory	-50 to - nt binar 10 r/w 1 2 r/w calibra	-50A. y 9 r Mantissa Variable 1 r/w	8 r		YES
		Sets the voltage lev VOUT_MODE comm	el for a nand. Al	lowed r	ange is	0.6 to 2\	√.			of -14 p	oer -	
		Format	4 -			two's co			•	1 -	4	
		Bit Position	15	14	13	12	11	10	9	8	4	
4.0	\/OUT O\/ E^\\\\\	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4	VEC
40	VOUT_OV_FAULT_LIMIT	Function Default Value					tissa				-	YES
		Bit Position	7	6	5		able	2	1	^	-	
		Access	7 r/w	6 r/w	r/w	r/w	7 r/w	r/w	1 r/w	0 r/w	1	
		Function	17 VV	1 / VV	1/ ۷۷		tissa	1/ ٧٧	1 / ۷۷	1/ ۷۷	1	
		Default Value					able				1	
		Instructs the modul	e on wh	nat actio	on to ta			:o an ou	ıtput ov	ervolta	<u>-</u> ge fault	
		Format				Unsigne	d Binary					
		Bit Position	7	6	5	4	3	2	1	0		
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0		

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120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief	Descri	ption					Non-Volatile Memory Storage		
		Sets the value of ou		lowed r	ange is	0.6 to 2	V.			for ove	er-voltage.			
		Format			inear, tv									
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r/w	r/w	r/w				
42	VOUT_OV_WARN_LIMIT	Function		E	Exponer			1	Mantiss	ב		YES		
		Default Value					able							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					tissa							
		Default Value				Vari	able							
	Sets the value of output voltage at which the module generates warning for under-volted Exponent is fixed at -14. Allowed range is 0.05 to 1.5V. Format Linear, two's complement binary													
		Bit Position	15		inear, tv	12	npieme 11	nt binar	у 9	8				
		Access		14				r/w	r/w	r/w				
43	VOUT UV WARN LIMIT	Function	r	r	r xponer	r	r		Mantisso			YES		
43	VOOT_OV_WARIN_LIIMIT	Default Value			-vhouse		able	<u> </u>	iui ilissi	<u>, </u>		153		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	1, **	1, 00	1,,,,		tissa	1, **	1,, **	1,7 00				
		Default Value					able							
		Sets the voltage lev range is 0.05 to 2V.	ets the voltage level for an output undervoltage fault. Exponent is fixed at -14. Allowed ange is 0.05 to 2V.											
		Format			inear, tv		mpleme	nt binar	У					
		Bit Position	15	14	13	12	11	10	9	8				
	VOUT_UV_FAULT_LIMIT	Access	r	r	r	r	r	r/w	r/w	r/w				
44		Function		E	Exponer			1	Mantiss	ב		YES		
		Default Value					able	1	1					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					tissa							
		Default Value				Vari	able							
		Instructs the modu	<u>le o</u> n wl	hat acti	on to ta	ke in re	sponse	to an ou	ıtput un	dervolt	age fault			
		Format					d Binar							
		Bit Position	7	6	5	4	3	2	1	0				
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES		
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х				
		Default Value	1	0	1	1	1	0	0	0				
		Sets the current lev maximum of 140A)		ponent	is fixed	at -2				d belov	v the			
		Format			inear, tv									
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r/w	r/w				
46	IOUT_OC_FAULT_LIMIT	Function	<u> </u>		xponer		I 6		Mantisso			YES		
		Default Value	1	1	1	1	0	0	1	0				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function			_		tissa	_	_	0				
		Default Value	0	0	0	0	ΙΙ	0	0	0				
L														

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex		Non-Volati												
Code	Command				Brief	Descri	ption					Memory Storage		
		Sets the value of cu	ırrent le	vel at w	hich th	e modu	e gener	ates w	arnina f	or over	current			
		Allowed range is 0						ates w	arriirig i	51 0 0 0 1 0	Jan Chi.			
		Format				vo's cor		nt bina	rv		1			
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r	r/w				
4A	IOUT_OC_WARN_LIMIT	Function		E	Exponer	nt		1	Mantisso	a		YES		
		Default Value	1	1	1	1	0	0	1	0				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function		1			tissa							
		Default Value	1	0	1	0	1	0	0	0				
		Sets the temperatu	re level	above v	which o	ver-tem	peratur	e fault	occurs.	Allowed	I range is 35			
		to 140°C. The expo									3			
		Format	Format Linear, two's complement binary											
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r/w	r	r				
4F	OT_FAULT_LIMIT	Function			Exponer				Mantiss			YES		
		Default Value	0	0	0	0	0	0	0	0				
		Bit Position	7 r/w	6 r/w	5 r/w	4 r/w	3 r/w	2 r/w	1 r/w	0 r/w				
		Access Function	I/W	I/W	I/W		tissa	I/W	I/W	I/W	-			
		Default Value	1	0	0	0	1	0	1	0				
		<u> </u>					Т	U		U				
			Configures the over temperature fault response Format Unsigned Binary											
50	OT_FAULT_RESPONSE	Bit Position	7	6	5	4	3	2	1	0		VEC		
50		Access	r/w RSP	r/w RSP	r/w	r/w	r/w	r	r	r		YES		
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	X	X	X				
		Default Value	1	0	1	1	1	0	0	0				
		<u> </u>	oratura	warnin	a loval :	م ۱۰۰۰	oured	anac ic	70+017	10°C TI-	0.0000000			
		Sets the over temper is fixed at 0.	erature	warnin	y ievel li	ı C. All	owea ro	unge is	50 to 13	o'C. In	e exponent			
			1		inac- 1	/c ===	mnle	: ما + م	n.		7			
		Format Bit Position	15	14	inear, to	vo's cor		nt bina	ry 9	8	1			
		Access	15 r	14 r	13 r	12 r	11 r	10	r	r	}			
51	OT WARN LIMIT	Function		1	Exponer		'		Mantiss		1	YES		
		Default Value	0	0	0	0	0	0	0	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0	1			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1			
		Function					tissa			•]			
		Default Value	0	1	1	1	1	1	0	1]			
		Sets the input over	voltage	fault lin	nit. Exp	onent is	fixed at	t -6. Allo	wed ra	nge is 6	.75 to 15V.			
		Format		L	inear, tv	vo's cor	npleme	nt binar	y.		1			
		Bit Position	15	14	13	12tr	11	10	9	8				
		Access	r	r	r	r	r	r	r/w	r/w]			
55	VINI OV ENTIT LIMIT	Function			Exponer				Mantiss			YES		
22	VIN_OV_FAULT_LIMIT	Default Value	1	1	0	1	0	0	1	1		TES		
		Bit Position	7	6	5	4	3	2	1	0]			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	1		1		tissa	I ^	1 0	I 0	-			
		Default Value	1	0	1	0	0	0	0	0	j			
		1												

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex	Communid	Brief Description											
Code	Command				Brie	Descri	ption					Memory Storage	
		Configures the VIN	overvol	tage fa							1		
		Format					d Binar						
		Bit Position	7	6	5	4	3	2	1	0			
56	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES	
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	X	X			
		Default Value	[1]	[0] 0	0	0	0	0	0	0			
		Sets the value of th at -6. Allowed rang				iuses irii	Jul Voil	ige iow	warnin	g. Expoi	nent lixed		
		Format	15 0.7 5			wo's coi	mpleme	nt hina	٢٧		1		
		Bit Position	15	14	13	12	11	10	9	8			
		Access	r	r	r	r	r	r	r/w	r/w			
57	VIN OV WARN LIMIT	Function			xponer	nt		ı	Mantiss			YES	
		Default Value	1	1	0	1	0	0	1	1			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function	<u> </u>		1 -		itissa			I 6	1		
L		Default Value	1	0	0	0	0	0	0	0	<u> </u>		
		Sets the value of th	e input	voltage	that co	iuses ini	out volto	age low	warnin	g. Expoi	nent fixed		
		at -6. Allowed rang		14V.						<u> </u>	-		
		Format					mpleme]		
		Bit Position	15	14	13	12	11	10	9	8	_		
		Access	r	r	r	r	r	r	r/w	r/w			
58 VIN_U\	VIN_UV_WARN_LIMIT	Function			Exponer	1			Mantiss			YES	
		Default Value	7	1 6	5	4	3	2	0	0			
		Bit Position Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function	1700	17 00	17 00		itissa	1700	17 00	1700			
		Default Value	1	0	1	0	0	0	0	0			
		at -6. Allowed rang	ts the value of the input voltage that causes an input undervoltage fault. Exponent fixed -6. Allowed range is 5 to 14V. Format Linear, two's complement binary										
			-						1				
		Bit Position	7	6	5	4	3	2	1	0			
59	VIN UV FAULT LIMIT	Access Function	r	r	r Exponer	r h	r	r	r/w Mantiss	r/w		YES	
59	VIN_UV_FAULT_LII*IIT	Default Value	1	1	0	1	0	0	0	1		YES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-		
		Function					itissa]		
		Default Value	1	0	1	0	0	0	0	0]		
		Instructs the modu	le on wh	nat acti	on to ta	ke in res	sponse t	to an in	put und	ervoltag	ge fault.		
		Format					d Binar						
		Bit Position	7	6	5	4	3	2	1	0			
5A	VIN_UV_FAULT_RESPONSE	Access	r/w RSP	r/w RSP	r/w	r/w	r/w	r	r	r		YES	
		Function	[1]	[O]	RS[2]	RS[1]	RS[0]	X	Х	X			
		Default Value	1	0	1	1	1	0	0	0]		
		Sets the output vol	tage lev	el at wh	nich the	PGOOD	pin is a	sserted	high. I	mplied (exponent of		
		-14 per VOUT_MOD		nand. A	Allowed	range is	6 0.09 to	1.65V.					
		Format					mpleme						
		Bit Position	15	14	13	12	11	10	9	8	1		
	000000	Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4	1450	
5E	POWER_GOOD_ON	Function					itissa				-	YES	
		Default Value Bit Position	7	6	5	Vari	able 3	2	1	0	-		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1		
		Function	1, 77	17 00	17 VV		itissa	1, 77	17 00	17 VV	1		
		Default Value Variable											
			1			v u i i	2210				1		

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex				Non-Volatile								
Code	Command				Brie	ef Desci	ription					Memory Storage
		Sets the output vol-	tage lev	el at wh	nich the	PGOOD	pin is c	le-asser	rted low	. Implied	exponent of	
		-14 per VOUT_MOD									_	
		Format			Linear,	two's co	mplem	ent bind	ary			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5F	POWER_GOOD_OFF	Function					ntissa					YES
		Default Value				Va	riable					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					ntissa					
		Default Value				Va	riable]	
		Sets the delay time	in ms c	of the ou	ıtput vo	ltage dı	uring sto	artup. A	llowed r	ange is 0	to 1000ms.	
		Format			Linear,	-	-				7	
		Bit Position	15	14	13	12	11	10	9	8	1	
		Access	r	r	r	r	r	r	r/w	r/w		
		Function			Exponer				Mantis			
60	TON_DELAY	Default Value	0	0	0	0	0	0	0	0	1	YES
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Ма	ntissa				1	
		Default Value	0	0	0	0	0	0	1	0		
-		Cata tha rica tima ir	n mc of	the out	out volte	ago duri	na star	up The	ovnon	ant is five	4 at 0	
		Sets the rise time in Allowed range is 1			Jul Voill	ige dun	ng stan	.up. me	expone	ent is fixed	auto.	
		Format	1000		Linear,	two's co	mnlem	ent hind	nrv.		7	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	R	r	r	r	r/w	r/w	1	
61	TON_RISE	Function			Exponer				Mantis		1	YES
01	1011_11132	Default Value	0	0	0	0	0	0	0	0		120
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function				Ма	ntissa				1	
		Default Value	0	0	0	0	0	1	0	1		
		Sets the delay time			utput vo	ltage dı	uring tu	n-off. T	he expo	nent is fix	ked at 0.	
		Allowed range is 0	to 1000		11	/					1	
		Format Bit Position	1 -		Linear,						1	
			15	14	13	12	11	10	9	8	1	
c 1.	TOEL DELAW	Access Function	r	r	R	r	r	r	r/w Mantis	r/w	1	VEC
64	TOFF_DELAY	Default Value	0	0	Exponer 0	0	0	0	0	0	1	YES
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	17 00	17 00	17 00		ntissa	1 / VV	17 VV	1 / VV	1	
		Default Value	0	0	0	0	0	0	1	0	1	
			l) Allow	
		Sets the fall time in		ne outp	ut volta	ge durii	ng turn-	отт. Ехр	onent is	s fixed at (J. Allowed	
		range is 0 to 1000n	115.		Linear,	two's co	mnlom	ant hin	an.		1	
		Bit Position	15	14	13	12	mpiem 11	ent bind	11y 9	8	1	
		Access	13	r	R	r	r	r	r/w	r/w	1	
65	TOFF_FALL	Function	<u> </u>	1	xponer		_ '	1	Mantis		1	YES
0.5	TOTT_I ALL	Default Value	0	0	_xponer_	0	0	0	0	0		ILJ
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	1, 00	1, **	1 1, 00		ntissa	1, ۷۷	1, 00	1, 1, 1	1	
		Default Value	0	0	0	0	0	1	0	1	1	
											1	

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120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command		Brief Description											
		Returns one byte o	f inform	ation v	vith a :	summar	v of the	e mo	st critical	modu	le faul	ts		
		Format					signed							
		Bit Position	7	6	Ĺ		4		3 2)	1	0		
78	STATUS_BYTE	Access	r	r	F		r		r r		r	r		
		Flag	Х	OFF	VOU.	Γ Ον ΙΟ	UT OC	VIN	_UV TEI	MP C	ML C	THER		
		Default Value		0			Varia			0		7111211		
		Delaalt value	l				varia	DIC						
		Returns two bytes	of inforn	nation	with a	summo	ary of th	ne m	odule's fo	ult/wo	ırning	condition	ons	
		Format				l	Insigne	d bir	nary					
		Bit Position	15	14		13	12		11	10	9	8		
		Access	r	r		R	r		r	r	r	r		
		Flag	VOUT	IOUT	OC	INPUT	Χ		PGOOD	Χ	Х	X		
79	STATUS_WORD	Default Value		_			Vari					ı		
		Bit Position	7	7 6		5	4	ubie	3	2	1	0		
		Access	r	r		R	r		r	r	r	r		
								0.0					_	
		Flag	Х	OFF	-	JU1_UV	1001_	_OC	VIN_UV	TEMP	CML	OTHE	۲	
		Default Value					Vari	able						
		Returns one byte o	eturns one byte of information with the status of the module's output voltage related faults											
		Format	Format Unsigned Binary											
		Bit Position	7		6		5		4	3	2	1 ()	
7A	STATUS_VOUT	Access	r		r		r		r	r	r	r ı	-	
	_	Flag	VOUT_	OV V	OUT_C Warn		UT_UV Warn	<u>'</u> - \	/OUT_UV	Х	Х	X >	<	
		Default Value			vvaiii			iable	<u> </u>	1				
		Returns one byte o	finform	ation	with th	o ctatuc	of tho	mod	ulo's outr	out cur	ront ro	olatod fa	nulte	
		Format		ution v	WILLI LII		ned Bi			out cui	i ent re		Juits	
		Bit Position	7		6 5		jileu bi	3		2 1	0	_		
7B	STATUS_IOUT	Access	r											
		Flag		IOUT_OC X X X IOUT_OC_WARN X X X										
		Default Value	1001_	_00			ariable		V/ II II V					
		Returns one b	yte of ir	nformo	ation w	ith the s	status c	of the	module'	s input	relate	d faults	3	
			<u>′</u>											
		Format Bit Position		7		6	Jnsigne	5	4	3	2	1 0		
		Access		<i>r</i>		r	-	<u>, </u>	r	r	r			
7C	STATUS_INPUT	Flag	VINI O	 / EALL	I T \/IN	1_OV_W	/ VIN_	111/	_		X	r r		
		ling	V11V_O	v_i AU		n_OV_V RNING	WAR				^	^ ^	'	
		Default Value				10		iable		<u>· I</u>		1	\exists	
			1											
		Returns one byte o	f inform	ation v	vith th				ule's tem	peratu	<u>re rel</u> c	ated fau	lts	
		Format	_				ned Bin		- I -	1 . 1				
7D	STATUS_TEMPERATURE	Bit Position	7	,		6		4	3 2	1	0			
		Access	o T		OT :	r		r	r r	r	r			
		Flag	OT_F/	AULI	UI_	WARN		Χ	X X	Χ	Χ			
		Default Value	<u> </u>			VC	ariable							
			of the Insigne		ule's com	ımunic	ation	related	faults					
		Format Bit Position	7		6	5		3	2	1		0		
75	CTATLIC CAN	Access	r		r	r		r	r			r	_	
7E	STATUS_CML	Flag	Inva Comm	lid	Invalio Data			Х		ner Cor				
		Default Value				1	Vari	iable					-	
		Deldalt value	l				vull	iable						

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex				•	mueu							Nor	n-Volatile			
Code	Command				Brief De	escription	on						ory Storage			
		Returns the value o	of the in	out volt	aae apr	olied to t	the mod	lule.								
		Format				vo's cor			У		1					
		Bit Position	15	14	13	12	11	10	9	8						
		Access	r	r	r	r	r	r	r	r						
00	DEAD VINI	Function			xponer		•	١	Mantiss	a						
88	READ_VIN	Default Value	Variable													
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function				Man	tissa									
		Default Value	Default Value Variable													
		Returns the value of	of the ou	ıtput vo	Itage of	the mo	dule. Ex	ponent	is fixed	d at -14						
		Format				vo's cor					1					
		Bit Position	15	14	13	12	11	10	9	8						
		Access	r	r	r	r	r	r	r	r	1					
0.0	BEAD VOLIT	Function				Man	tissa									
8B	READ_VOUT	Default Value				Vari	able									
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function					tissa			•						
		Default Value				Vari	able									
		Returns the value o	of the ou	itput cu	rrent of	the mo	dule.									
		Format				vo's cor		nt binar	У		1					
00		Bit Position	15	14	13	12	11	10	9	8						
		Access	r	r	r	r	r	r	r	r						
	DEAD JOHT	Function			xponer	nt	•	1	Mantiss	a						
8C	READ_IOUT	Default Value				Vari	able									
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function					tissa									
		Default Value	Variable								<u> </u>					
		Returns a module F	FET package temperature in °C.													
		Format		L	inear, tv	vo's cor	npleme	nt binar	У		1					
		Bit Position	15	14	13	12	11	10	9	8	1					
		Access	r	r	r	r	r	r	r	r	1					
0.0	DEAD TEMPERATURE 1	Function		E	xponer	nt		1	Mantiss	а						
8D	READ_TEMPERATURE_1	Default Value				Vari	able									
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function					tissa									
		Default Value				Vari	able				<u> </u>					
		Returns the module	PWM o	controlle	er temp	erature	in °C.						· · · · · · · · · · · · · · · · · · ·			
		Format				vo's cor		nt binar	У]					
		Bit Position	15	14	13	12	11	10	9	8						
		Access	r	r	r	r	r	r	r	r	1					
0.5	DEAD TEMPERATURE C	Function		Е	xponer	nt	Mantissa									
8E	READ_TEMPERATURE_2	Default Value				Vari	able									
		Bit Position	7	6	5	4	3	2	1	0						
		Access	r	r	r	r	r	r	r	r						
		Function					tissa			•						
		Default Value				Vari	able]					

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief De	escriptio	on					Non-Volatile Memory Storage		
		Returns the switchi				onverter	. The Fr	equenc	y is in K	ilohertz	and			
		Format				vo's cor	nnleme	nt bina	rv					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r	r				
95	READ FREQUENCY	Function				Inte	eaer							
33	NEND_I NEQUEIVET	Default Value	0	0	0	0	0	0	0	1				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	·			Inte				· ·				
		Default Value	1	0	0	1	0	0	0	0				
		Returns one byte in	Returns one byte indicating the module is compliant to PMBus Spec. 1.1											
		Format				Unsigne								
98	98 PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0		YES		
	_	Access	r	r	r	r	r	r	r	r				
		Default Value	0	0	0	1	0	0	0	1				
		<u> </u>												
		Value used to prog Block. Allowable ra		922 to	+10922	. Use po	sitive v	alues or	nly .	ensation	1			
		Format				vo's cor								
		Bit Position	15	14	13	12	11	10	9	8				
	MFR_SPECIFIC_KP	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
В0		Function					eger					YES		
		Default Value				Vari								
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Inte								
		Default Value				Vari	able							
		Value used to prog Allowable range: -1							mpenso	ition Bloo	ck.			
		Format		L	inear, tv	vo's cor	npleme	nt bina	ry					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
В1	MFR SPECIFIC KI	Function				Inte	eger					YES		
		Default Value				Vari	able							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function				Inte								
		Default Value				Vari	able							
		Value used to program specific differential coefficient of the PID compensation. Allowable range: -10922 to +10922. Use positive values only												
						vo's cor			ſV					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
B2	MFR SPECIFIC KD	Function					eger			•				
		Default Value				Vari						YES		
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					ger							
		Default Value				Vari	able							
		Value used to progr Allowable range: -2	ram spe	ecific alp	ha valu	ue of the	PID co	mpenso	ation blo	ock				
		Format	1 20 10 10			vo's cor		nt hina	٦٧					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
В3	MFR_SPECIFIC_ALPHA	Function	17 VV	1 / VV	1 / ۷۷			1 / ۷۷	1 / ۷۷	17 00		VES		
دم	I'II N_SELCIFIC_ALPHA	Function Integer Default Value Variable								YES				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	1, 00	17 VV	1, 77		eger	1, 00	1 / ۷۷	17 00				
		Default Value					able							
		Delaut Value	l			vuil	abic							

GE

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command	Brief Description									Non-Volatile Memory Storage					
Code		Returns module no	me infor	mation	(read c	nnly)						Plemory Storage				
		Format	1		,, caa (Unsign	ed Bind	iry			1					
		Bit Position	15	14	13	12	11	10)	9 8						
		Access	r	r	r	r	r	r		r r						
50	MED CDECIEIC 00	Function		•		Res	erved			•		VEC				
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0		0 0		YES				
	Bit Position	7	6	5	4	3	2		1 0							
		Access	r	r	r	r	r	r		r r						
		Function			Module	e Name)			Reserved						
		Default Value	0	0	1	1	0	1		0 0						
		Applies an offset to in module measure Exponent is fixed a	ements o	f the ou	itput vo	oltage (betwee	en -12	5mV a							
D4 MFR_READ_VOUT_CAL_OFFSET	Format	45			wo's co				0 1 0							
	Bit Position	15	14	13	12	11	10		9 8							
	Access	r/w	r/w	r/w	r/w	r/w	r/\	N I	/w r/w	-	YES					
	_ 	Function Default Value	1	1/05	iahla h	Mai ased or	ntissa Nfactor	.v.cal:L	oratio-	<u> </u>	4					
		Bit Position	7	6	5	used or	3	2		1 0	1					
	Access	r/w	r/w	r/w	r/w	r/w			/w r/w	1						
		Function	1, 00	1 / ۷۷	17 VV		ntissa	1/\	·• 1	, •• 1, ••	1					
		Default Value	†	Vari	iable bo	ased or		v calil	oration	1	1					
		Applies a gain corr	ection to	the RE	AD_VO	UT com	mand	result	s to co	llibrate out	gain					
		divided by 8192 to								una regis	, cci 13					
		Format	generate			wo's co		ent bi	narv							
D5 MFR_		Bit Position	15	14	13	12	11	10		9 8						
		Access	r/w	r/w	r/w	r/w	r/w			/w r/w						
	MFR_READ_VOUT_CAL_GAIN	Function	.,	.,			eger		· ·			YES				
		Default Value		Vari	iable bo	ased or		y calil	oration	1						
		Bit Position	7	6	5	4	3	2		1 0						
		Access	r/w	r/w	r/w	r/w	r/w	r/\	v r	/w r/w						
		Function					eger									
		Default Value	Default Value Variable based on factory calibration													
		Applies an offset to the commanded output voltage to calibrate out errors in setting module output voltage (between -63mV and +62mV) when using Trim resistor. Exponent is fixed at -14.														
		Format				wo's co										
		Bit Position	15	14	13	12	11	10		9 8	1					
D7	MFR_VOUT_CAL_OFFSET	Access	r/w	r/w	r/w	r/w	r/w	r/\	v r	/w r/w	_	YES				
"	. II N_VOO1_CAL_OI 1 3E1	Function	1				ntissa	***			4	125				
		Default Value	 -			ased or					4					
		Bit Position	r/	6	5	r/w	3	2		1 0 /w r/w	4					
		Access Function	r/w	r/w	r/w		r/w ntissa	r/\	v I	/w r/w	1					
		Default Value	+	Vari	iable br	ased or		v calil	oration	1	1					
-			rmine wh					_				VFS				
		Bit 7 used to dete VOUT_COMMAND).		·	•					-	YES				
		Bit 7: 1 – Output v				i rim vo	ilue an	a can	pe ad	justed from	set					
		value using the V					OMM^	NID ~~	d car	ha adiusta	4					
		Bit 7: 0 – Output v from set value usi						מט טאו	u can	ne adjuste	J					
		Bit 0: Used to indi						ide to	the Va	nut set noin	t PG					
		On/Off levels, mai									., ı U					
D8	MFR_VOUT_SET_MODE	indicates that one									s bit					
	_ _ _ _	is 0, then the defo					3,1				-					
		Format Bit Position	7	6	5	4	gnea B 3	inary 2	1	0						
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w						
	•		VOUT_SI	_												
		Flag	T_MODE		X	X	Χ	Χ	X	USER_CHA	ANGES					
		Default Value	1	0	0	0	0	0	0	0						
_																

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 4 (Continued)

Hex Code	Command				Brief	f Descri	ption						Non-Volatile Memory Storage
		Value used to progi	ram the	firmwa	ro rovic	ion This	comm	and is r	and anl	\ /			rionioi) otorago
		Format	un the					nt binar		у.	7		
	MFR_FW_REVISION	Bit Position	15	14	13	12	11	10	9	8			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function	1,700	1,00				_	1, 00	1,7 **			
DB		Default Value	Integer – Major Version Variable										
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function		l l	Inte	aer – M	inor Ver	sion					
		Default Value					able						
DD	MFR_RTUNE_INDEX	Returns the index d is from 0 to 59. Format Bit Position Access Function Default Value	erived f	rom the		Jnsigne 4 r Inte	ed to the d Binary 3 reger able		IE pin o	f the n	nodule.	. Range	YES
DF	MFR_WRITE_PROTECT	corresponding PME Format Bit Position Access Function Default Value Bit Position Access Function Default Value Bit 0: ON_OFF_CON Bit 1: IOUT_OC_FAU Bit 2: OT_FAULT_LIR Bit 3: OT_FAULT_RE	Bit Position 15 14 13 12 11 10 9 8 Access r								YES		
FO	MFR_MODULE_DATE_LOC _SN	YY : year of manufa FF: Factory where r WW: Fiscal week of	Bits 4 – 15: Reserved Read only command which returns 12 bytes with the value of YYFFWWXXXXXX, where /Y: year of manufacture FF: Factory where manufactured WW: Fiscal week of the year when unit was manufactured XXXXXX: Unique number for the specific unit – corresponding to serial number on the label of the unit									YES	

SMBALERT# is also triggered:

- when an invalid/unrecognized PMBus command (write or read) is issued
- By invalid PMBus data (write)
- By PEC Failure (when used)
- By Enable OFF (when used)
- Module is out of Power Good Range

Digital Power Insight (DPI)

GE offers a software tool that set helps users evaluate and simulate the PMBus performance of the TJT170A modules without the need to write software.

The software can be downloaded for free at http://go.ge-energy.com/DigitalPowerInsight.html. A GE USB to I2C adapter and associated cable set are required for proper functioning of the software suite. For first time users, the GE DPI Evaluation Kit can be purchased from leading distributors at a nominal price and can be used across the entire range of GE Digital POL Modules.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 37. The preferred airflow direction for the module is in Figure 38.

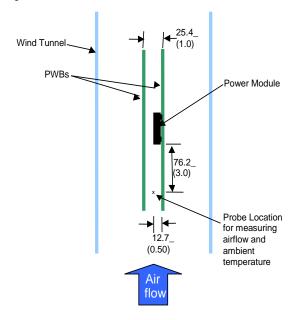


Figure 37. Thermal Test Setup.

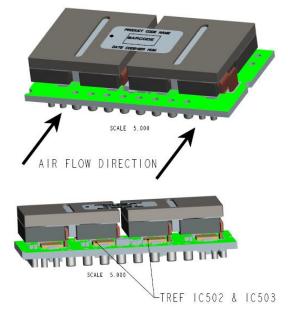


Figure 38. Preferred airflow direction and location of hotspots of the module (Tref).

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 38. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Example Application Circuit

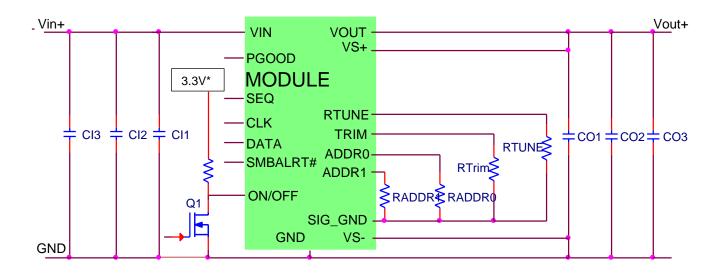
Requirements:

Vin: 12V Vout: 1.2V

lout: 120A max., worst case load transient is from 60A to 90A, 10A/usec

ΔVout: 25mV for worst case load transient

Vin, ripple 2% of Vin (240mV p-p)



3.3V* can be derived from Vin through a suitable voltage divider network

CII $4 \times 0.047 \,\mu\text{F}$ (high-frequency decoupling ceramic capacitor)

CI2 $12 \times 22 \mu F$ Ceramic

CI3 $4 \times 470 \mu F$ (polymer or electrolytic)

CO1 $4 \times 0.047 \mu F$ (high-frequency decoupling ceramiccapacitor)

CO2 $12 \times 47 \mu F$, Ceramic

CO3 $7 \times 1000 \, \mu F$ RTune $2460 \, \Omega$, RTrim $5.9 K \Omega$

<u>Note:</u> The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the PMBus master controller will have pull-up resistors as well as provide the driving source for these signals.

If running the simulation at ge.transim.com remember to use bin 'a' parameters to determine the Loop Stability, and bin 'b' parameters to determine the transient response.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

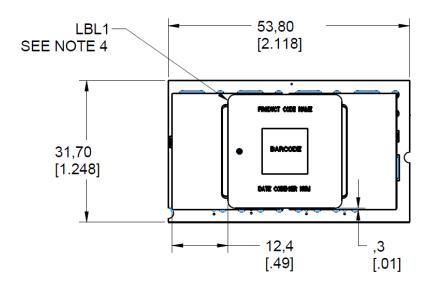
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Mechanical Outline (SMT)

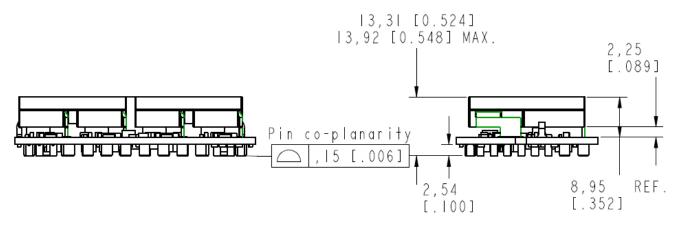
Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

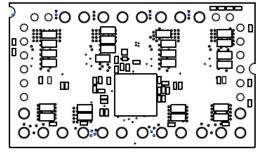
x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



TOP VIEW



FRONT VIEW SIDE VIEW



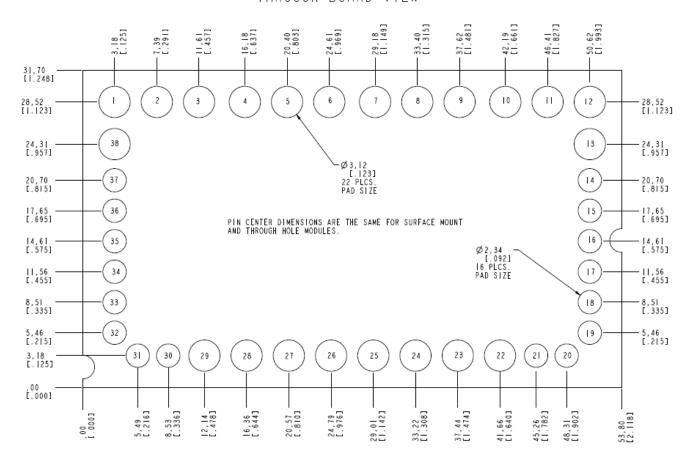
BOTTOM VIEW

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Recommended SMT Pad Layout

RECOMMENDED SMT FOOTPRINT -THROUGH BOARD VIEW -



PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

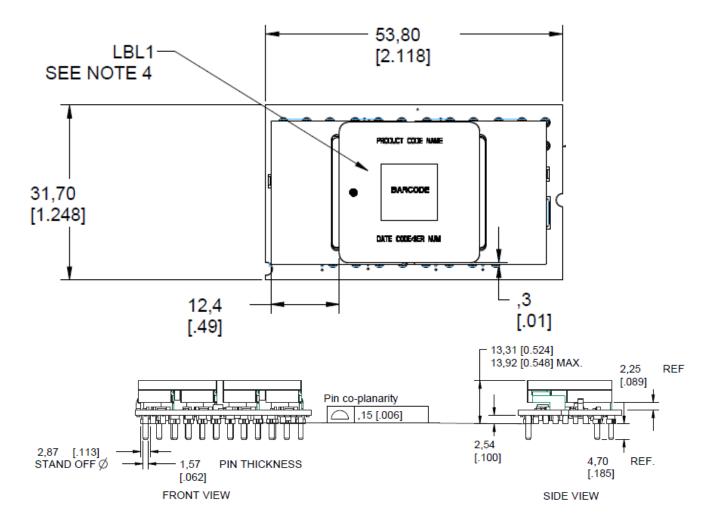
120A TeraDLynx™: Non-Isolated DC-DC Power Modules

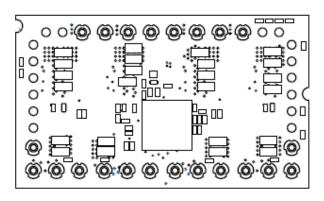
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Mechanical Outline (Through hole)

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated] x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



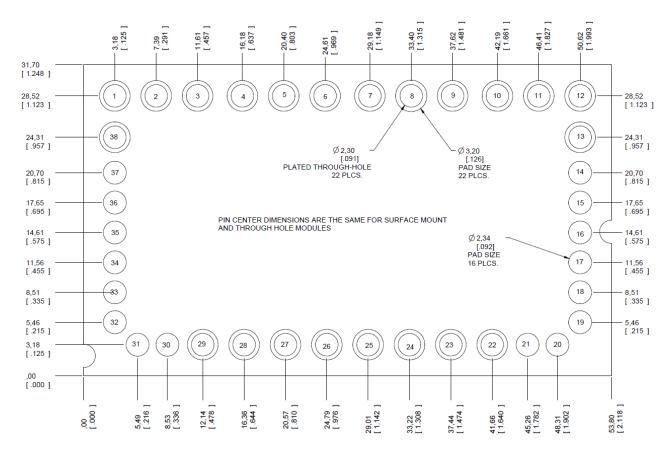


BOTTOM VIEW

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Recommended Through-hole Layout



Note: In the Through-Hole version of the TJT120, pins 1-13, 22-29 and 38 are Through-Hole pins, pins 14-21, 30-37 are SMT pins. The drawing above shows the recommended layout as a combination of holes in the PWB to accommodate the Through-Hole pins and pads on the top layer to accommodate the SMT pins.

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND*	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

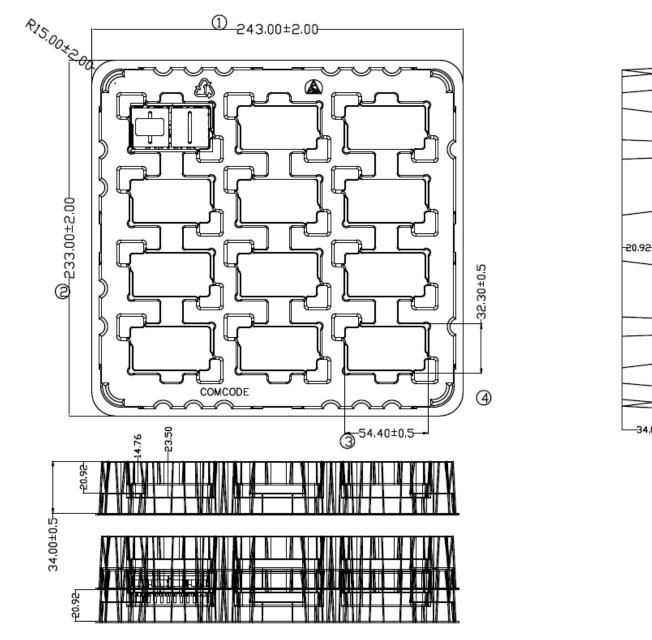
^{*}Do not connect SIG_GND to any other GND paths. It needs to be kept separate from other grounds on the board external to the module

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Packaging Details

The 120A TeraDLynxTM modules are supplied in trays. Modules are shipped in quantities of 12 modules per layer, 24 per box. All Dimensions are in millimeters and (in inches).



120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Surface Mount Information Pick and Place

The 120A TeraDLynx[™] modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 15mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 22 mm.

Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 120A TeraDLynx $^{\text{TM}}$ modules have a MSL rating of 3.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at

conditions of \leq 30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.

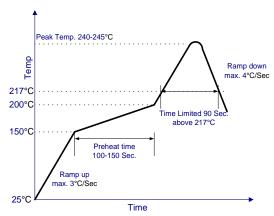


Figure 39. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).

Through Hole Information

The 120A TeraDLynx[™] modules are lead-free (Pb-free) and RoHS compliant and fully compatible in an Pb-free soldering process. For the through-hole application, it is recommended that the modules are assembled in the pin and paste reflow process, not in the wave solder process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

GE

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 5. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Interconnect	Comcodes
TJT120A0X3Z	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	TH	150043982
TJT120A0X43Z	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Positive	TH	150049601
TJT120A0X3-SZ	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	SMT	150041745
TJT120A0X43-SZ	7 – 14Vdc	0.6 - 1.5 Vdc	120A	Positive	SMT	150049603

⁻Z refers to RoHS compliant parts

Table 6. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current		On/Off logic	Remote Sense	Options		ROHS Compliance
Т	J	Т	120A0	X		3	-SR	-H	Z
P=Pico U=Micro M=Mega G=Giga T=Tera	J = DLynx II	T=with EZ Sequence X=without sequencing	120A	able	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel No entry = Through hole	Extra Ground Pins	Z = ROHS6

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